Algorithmic Game Theory

Algorithmische Spieltheorie

Hedonic Games Wintersemester 2022/2023

Dozent: Prof. Dr. J. Rothe

hhu,

J. Rothe (HHU Düsseldorf)

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Hedonic Games



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Hedonic Games



Players, strategies, coalitions, and utility. Every player wants to maximize her payoff.

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Hedonic Games



Players, strategies, coalitions, and utility. Every player wants to maximize her payoff. Voters, candidates, and preferences.

Winners determined by a voting system.

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Hedonic Games



Players, strategies, coalitions, and utility. Every player wants to maximize her payoff. Players, coalitions, and preferences. Every player wants to join her most preferred coalition. Voters, candidates, and preferences.

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Hedonic Games

- A hedonic game is a pair (N, \succeq) with
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Definition (Drèze & Greenberg (1980))

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• $\Gamma(i)$ denotes the coalition of Γ that contains player $i \in N$. J. Rothe (HHU Düsseldorf) Algorithmic Game Theory

Example of a Hedonic Game



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preferences: $\{1,3\} \succ_1 \{1,2\} \succ_1 \{1\} \succ_1 \cdots$

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Compact Representations of Hedonic Games

• Individually rational hedonic games (Ballester, GEB 2004):

Players list their individually rational coalitions only; those that they weakly prefer to being alone.

- Anonymous hedonic games (Ballester, GEB 2004):
 Players are indifferent about coalitions of equal size.
- Singleton encoding of hedonic games (Cechlárová & Romero-Medina, IJGT 2001):

Every player ranks single players only rather than coalitions of players.

• Hedonic coalition nets (Elkind & Wooldridge, AAMAS 2009):

a rule-based representation for hedonic games that is universally expressive.

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Compact Representations of Hedonic Games

• Additive hedonic games (Aziz, Brandt, & Seedig, AIJ 2013):

Each player *i* has a preference function $v_i : N \to \mathbb{R}$ such that for all coalitions $C, D \subseteq N$, we have $C \succeq_i D$ if and only if

$$\sum_{j\in C} v_i(j) \ge \sum_{j\in D} v_i(j).$$

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• Fractional hedonic games (Aziz, Brandt, & Harrenstein, AAMAS 2014): Every player assigns some value to each other player and 0 to herself; player *i*'s utility of a coalition is her average value assigned to the members of this coalition; and for all coalitions $C, D \subseteq N$, we have $C \succeq_i D$ if and only if *i*'s utility of *C* is at least as high as her utility of *D*.

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- Friend-oriented and enemy-oriented encoding (Dimitrov, Borm, Hendrickx, & Sung, SCW 2006).

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Friends and Enemies

Definition (Dimitrov, Borm, Hendrickx, & Sung (SCW 2006))

Let (N,\succeq) be a hedonic game. For each $i \in N$, partition $N \setminus \{i\}$ into

- the set $F_i \subseteq N \setminus \{i\}$ of friends of player *i*, and
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A preference relation \succeq_i is called *enemy-oriented* if it holds that $C \succeq_i D \iff$ $\|C \cap E_i\| < \|D \cap E_i\|$ or $\|D \cap E_i\| = \|D \cap E_i\|$ or

 $(\|C \cap E_i\| = \|D \cap E_i\| \text{ and } \|C \cap F_i\| \ge \|D \cap F_i\|),$

for all $i \in N$ and all coalitions $C, D \subseteq N$ with $i \in C \cap D$.



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Here, only *symmetric* friendship relations matter.



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Friends and Enemies

Definition (Dimitrov, Borm, Hendrickx, & Sung (SCW 2006))

Let (N,\succeq) be a hedonic game. For each $i \in N$, partition $N \setminus \{i\}$ into

- the set $F_i \subseteq N \setminus \{i\}$ of friends of player *i*, and
- the set $E_i = N \setminus (F_i \cup \{i\})$ of enemies of *i*.

A preference relation \succeq_i is called *friend-oriented* if it holds that $C \succeq_i D \iff$

 $||C \cap F_i|| > ||D \cap F_i||$ or

 $(\|C \cap F_i\| = \|D \cap F_i\| \text{ and } \|C \cap E_i\| \le \|D \cap E_i\|),$

for all $i \in N$ and all coalitions $C, D \subseteq N$ with $i \in C \cap D$.

Here, only *symmetric* friendship relations matter.



Friend- and Enemy-Oriented Preferences Are Additive

Definition

A hedonic game (N, \succeq) is said to be *additive* if every player $i \in N$ has a preference function $v_i : N \to \mathbb{R}$ such that

$$C \succeq_i D \iff \sum_{j \in C} v_i(j) \ge \sum_{j \in D} v_i(j).$$

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In particular, enemy-oriented preferences are additive:

- Set $v_i(j) = 1$ if *i* considers *j* a friend.
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Similarly, friend-oriented preferences are additive:

- Set $v_i(j) = ||N||$ if *i* considers *j* a friend.
- Set $v_i(j) = -1$ if *i* considers *j* an enemy.

Core Stability

Definition (Drèze & Greenberg (1980))

Let (N, \succeq) be a hedonic game.

- A nonempty coalition $C \subseteq N$
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 - *core stable* if there is no blocking coalition;
 - strictly core stable if there is no weakly blocking coalition.



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Example

Five players 0, 1, 2, 3, 4 are sitting (in this order) around a round table. Every player *i* (modulo 5 throughout) assigns

- a value $v_i(i+1) = 1$ to the player to his right,
- a value $v_i(i-1) = 2$ to the player to his left, and
- a value -4 to the remaining two players.

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In the only remaining case for a potentially core stable partition, there is one single-player coalition $\{i\}$ and two two-player coalitions $\{i+1, i+2\}$ and

 $\{i+3, i+4\}$; this partition is blocked by $\{i, i+1\}$.

J. Rothe (HHU Düsseldorf)

Algorithmic Game Theory

Wonderful Stability

Definition (Woeginger (SOFSEM 2013)) Let G = (V, E) be an undirected graph.

 The clique number ω_G(v) of v in G is the size of a largest clique in G that contains v.

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Wonderful Stability

Example



The partition Π into cliques indicated by the dashed lines is wonderfully stable since every vertex is in a clique of maximum size.

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Wonderful Stability vs Strict Core Stability



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Wonderful Stability vs Strict Core Stability





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Wonderful Stability vs Strict Core Stability



Lemma

Let G = (V, E) be the graph representation of the enemy-oriented hedonic game $\mathscr{G} = (N, \succeq)$. Let Π be a partition of V and Γ the corresponding coalition structure in \mathscr{G} .

- If Π is a wonderfully stable partition for G, then Γ is a strictly core stable coalition structure for G.
- 2 If there is an integer c ∈ N such that ω_G(v) = c for all vertices v ∈ V and Γ is a strictly core stable coalition structure for 𝒢, then Π is a wonderfully stable partition for G.

J. Rothe (HHU Düsseldorf)

Challenge: Wonderful Stability

Open Problem (Woeginger (SOFSEM 2013))

Pinpoint the computational complexity of deciding whether a given undirected graph has a wonderfully stable partition.

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Definition

• DP = { $A \setminus B \mid A, B \in NP$ }.

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$$DP = \{A \setminus B \mid A, B \in NP\}.$$

• $P^{NP[log]} = \Theta_2^p = P_{\parallel}^{NP} = \begin{cases} A \mid (\exists DPOTM \ M)(\exists B \in NP) \\ [A = L(M^B) \text{ and all queries to} \\ \text{the oracle } B \text{ are asked in parallel} \end{cases}$

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• $P^{NP[log]} = \Theta_2^p = P_{\parallel}^{NP} = \begin{cases} A \mid (\exists DPOTM \ M) (\exists B \in NP) \\ [A = L(M^B) \text{ and all queries to} \\ \text{the oracle } B \text{ are asked in parallel} \end{cases}$
• $\Sigma_2^p = NP^{NP} = \{A \mid (\exists NPOTM \ N) (\exists B \in NP) [A = L(N^B)]\}.$

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By definition, $P \subseteq NP \subseteq DP \subseteq P^{NP[\log]} \subseteq \Sigma_2^p$.

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By definition, $P \subseteq NP \subseteq DP \subseteq P^{NP[log]} \subseteq \Sigma_2^p$. $P^{NP[log]}$ -completeness is known, e.g., for the winner problems in

- Dodgson (Hemaspaandra, Hemaspaandra, & Rothe, JACM 1997),
- Young (Rothe, Spakowski, & Vogel, TOCS 2003), and
- Kemeny elections (Hemaspaandra, Spakowski, & Vogel, TCS 2005).

CORE STABLE PARTITION EXISTENCE (CSPE)

Given: A hedonic game (N, \succeq) .

Question: Does there exist a core stable partition of *N*?

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CORE STABLE PARTITION VERIFICATION (CSPV)

Given: A hedonic game (N, \succeq) and a partition Π of N.

Question: Does there exist a blocking coalition for partition Π ?

Remark (Woeginger (SOFSEM 2013))

Suppose the preferences can be evaluated in polynomial time, i.e., $\{(i, C, D) \mid i \in N \text{ and } C, D \subseteq N \text{ and } C \succeq_i D\} \in P.$

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- $CSPV \in NP$, as we can check in P whether a given $C \subseteq N$ blocks Π ;
- CSPE $\in \Sigma_2^p$, as $(N, \succeq) \in CSPE \iff (\exists \Pi) (\forall C \subseteq N) [\neg (C \ blocks \Pi)].$

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Complexity Theory

Core Stability Problems

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Observation (Woeginger (SOFSEM 2013))

• $CSPV \in P \Rightarrow CSPE \in NP.$

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Observation (Woeginger (SOFSEM 2013))

- $CSPV \in P \Rightarrow CSPE \in NP.$
- However, hardness of CSPV does not necessarily imply hardness of CSPE.

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Core Stability under Enemy-Oriented Preferences:

Theorem (Dimitrov, Borm, Hendrickx, & Sung (SCW 2006))

Under enemy-oriented preferences, there always exists a core stable partition; hence $CSPE \in P$.

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Theorem (Sung & Dimitrov (ORL 2007))

Under enemy-oriented preferences, CSPV is NP-complete.

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Core Stability under Enemy-Oriented Preferences: Challenge

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Open Problem (Woeginger (SOFSEM 2013))

Pinpoint the computational complexity of deciding whether a given hedonic game with enemy-oriented preferences has a strictly core stable partition.

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Complexity Theory

Core Stability under Additive Preferences

Corollary (Sung & Dimitrov (ORL 2007 and EJOR 2010)) For additive preferences, CSPV is NP-complete and CSPE is NP-hard.

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Core Stability under Additive Preferences

Corollary (Sung & Dimitrov (ORL 2007 and EJOR 2010)) For additive preferences, CSPV is NP-complete and CSPE is NP-hard.

Theorem (Aziz, Brandt, & Seedig (AIJ 2013)) Under symmetric additive preferences, CSPE is NP-hard.

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Theorem (Aziz, Brandt, & Seedig (AIJ 2013)) Under symmetric additive preferences, CSPE is NP-hard.

Theorem (Woeginger (MSS 2013))

In additive hedonic games, CSPE is Σ_2^p -complete.

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WONDERFULLY STABLE PARTITION EXISTENCE (WSPE)

Given: An undirected graph G = (V, E).

Question: Does there exist a wonderfully stable partition for *G*?

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Wonderfully Stable Partition Existence (WSPE)

Given: An undirected graph G = (V, E).

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WONDERFULLY STABLE PARTITION VERIFICATION (WSPV)

Given: A graph G = (V, E) and a partition Π of V into cliques.

Question: Does there exist a clique $C \subseteq V$ that blocks Π ?

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WONDERFULLY STABLE PARTITION VERIFICATION (WSPV)

Given: A graph G = (V, E) and a partition Π of V into cliques.

Question: Does there exist a clique $C \subseteq V$ that blocks Π ?

Again, WSPV and WSPE are closely related:

- $(G,\Pi) \in WSPV \iff (\exists clique C)[C blocks \Pi];$
- $G \in WSPE \iff (\exists \Pi)(\forall \text{ cliques } C)[\neg(C \text{ blocks } \Pi)].$

So WSPV \in NP and WSPE $\in \Sigma_2^p$.

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Theorem

WSPV is NP-complete.

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Theorem WSPV *is* NP-complete.

Theorem (Woeginger (SOFSEM 2013))

WSPE is NP-hard, and belongs to Θ_2^p .

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Theorem WSPV is NP-complete.

Can we also get coNP-hardness?

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Theorem (Woeginger (SOFSEM 2013)) WSPE is NP-hard, and belongs to Θ_2^p .

Theorem (Rey et al. (AMAI 2015)) WSPE *is* coNP-*hard*.



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Results

Wonderfully Stable Partition Problems

Theorem WSPV *is* NP-complete.

Theorem (Woeginger (SOFSEM 2013)) WSPE is NP-hard, and belongs to Θ_2^p .

Theorem (Rey et al. (AMAI 2015)) WSPE *is* coNP-*hard*. Can we also get coNP-hardness?

CAN WE DO BETTER?



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Results

Wonderfully Stable Partition Problems

Theorem WSPV *is* NP-complete.

Theorem (Woeginger (SOFSEM 2013)) WSPE is NP-hard, and belongs to Θ_2^p .

Theorem (Rey et al. (AMAI 2015)) WSPE *is* coNP-*hard*.

Theorem (Rey et al. (AMAI 2015)) WSPE is DP-hard. Can we also get coNP-hardness?

CAN WE DO BETTER?



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Results

Wonderfully Stable Partition Problems

Theorem WSPV *is* NP-complete.

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Proof: is inspired by the proof of Sung & Dimitrov (ORL 2007) that CSPV is NP-complete under enemy-oriented preferences.

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Theorem WSPV *is* NP-complete.

Proof: is inspired by the proof of Sung & Dimitrov (ORL 2007) that CSPV is NP-complete under enemy-oriented preferences.

NP-hardness is shown via a reduction from the NP-complete problem

	Clique
Given:	An undirected graph $G = (V, E)$ and a positive integer k.
Question:	Does G have a clique of size at least k ?

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Given an instance (G = (V, E), k) of CLIQUE, we construct the following graph G' = (V', E'):

- The vertex set V' is obtained from V by adding, for each $v \in V$, k-2 vertices.
- We connect each of the k − 2 new vertices and v to form a clique of size k − 1, for each v ∈ V.
- The edge set E' consists of these new edges and all edges in E.
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This can obviously be achieved in polynomial time.

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We claim that there is a clique of size k in G if and only if there exists a clique $C \subseteq V'$ that blocks Π in G'.

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The vertices $v \in C$ thus have a clique number $\omega_{G'}(v)$ of at least k.

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Since the size of all cliques in Π is k-1, there exists a vertex v in the clique C with $\omega_{G'}(v) > \|\Pi(v)\|$; therefore, C blocks Π in G'.

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If: If there is no clique of size k in G, there is no clique of size k in G', either, and $\omega_{G'}(v) = k - 1$ holds for each $v \in V'$.

We claim that there is a clique of size k in G if and only if there exists a clique $C \subseteq V'$ that blocks Π in G'.

Only if: If there is a size-k clique C in G, the same clique can be found in G'.

The vertices $v \in C$ thus have a clique number $\omega_{G'}(v)$ of at least k.

Since the size of all cliques in Π is k-1, there exists a vertex v in the clique C with $\omega_{G'}(v) > \|\Pi(v)\|$; therefore, C blocks Π in G'.

If: If there is no clique of size k in G, there is no clique of size k in G', either, and $\omega_{G'}(v) = k - 1$ holds for each $v \in V'$.

Furthermore, $\|\Pi(v)\| = k - 1$, for each $v \in V'$. Thus, there is no blocking clique for Π in G'.

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STRICTLY CORE STABLE COALITION STRUCTURE (SCSCS)

Given: A hedonic game (N, \succeq) with enemy-oriented preferences.

Question: Is there a strictly core stable coalition structure for (N, \succeq) ?

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CAN WE DO BETTER?

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J. Rothe (HHU Düsseldorf)

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Theorem (Rey et al. (AMAI 2015)) SCSCS *is* DP-*hard*.

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Consider the class of graphs G = (V, E) where all vertices have the same fixed clique number: ω_G(v) = k for all v ∈ V.

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- Consider the class of graphs G = (V, E) where all vertices have the same fixed clique number: ω_G(v) = k for all v ∈ V.
- Let *k*-WSPE and *k*-SCSCS denote the restrictions of WSPE and SCSCS to this special graph class.

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Theorem

For $k \ge 3$, k-WSPE (and thus k-SCSCS) is NP-complete.

J. Rothe (HHU Düsseldorf)

Open Problem (Woeginger (SOFSEM 2013))

Pinpoint the computational complexity of deciding whether a given enemy-oriented hedonic game has a strictly core stable partition.

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Open Problem (Woeginger (SOFSEM 2013))

- Pinpoint the computational complexity of deciding whether a given enemy-oriented hedonic game has a strictly core stable partition.
- Pinpoint the computational complexity of deciding whether a given undirected graph has a wonderfully stable partition.

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- Pinpoint the computational complexity of deciding whether a given undirected graph has a wonderfully stable partition.
 - One approach of showing Θ₂^p-hardness of WSPE is to generalize the construction for showing DP-hardness.

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Future Work

Challenge: Are WSPE and **SCSCS** Θ_2^p -Hard?

Open Problem (Woeginger (SOFSEM 2013))

- **Operational Complexity** of deciding whether a given enemy-oriented hedonic game has a strictly core stable partition.
- **Pinpoint the computational complexity** of deciding whether a given 2 undirected graph has a wonderfully stable partition.
 - One approach of showing Θ_2^p -hardness of WSPE is to generalize the construction for showing DP-hardness.
 - coDP-hardness of WSPE also implies Θ_2^p -hardness of WSPE, and the same argument works for SCSCS as well.

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 - It is also possible that both problems belong to DP (and so would be DP-complete) or are complete for another class.

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Algorithmic Game Theory